

# MMR+ANPR REST Server 3.0.2 User Guide

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# 1 Introduction

Eyedea Recognition's MMR+ANPR REST Server is a Java server application with REST interface running on Tomcat Docker container which allows to detect vehicle license plates or vehicles in input images and recognize the text and type of detected license plates, as well as the view, category, make, model, generation, variation, color and tags (various traits) of the vehicle.

MMR+ANPR REST Server uses our state-of-the-art libraries, LPM and MMR SDK, with a possibility to easily switch to the latest models or modules for a different region. Both server REST interface and the simple web application built on it provide the detection and recognition used in various use cases, as well as server monitoring.

# 2 Hardware requirements

# 2.1 Minimal requirements

- Processor: Intel® Core<sup>TM</sup> i5, 2 cores (4 logical processors)
- RAM: 4 GB
- Hard disk: 256 GB (optional SSD)
- GPU (optional): NVIDIA Driver version >= 410.48 compatible
- Operating system: Ubuntu 18.04 and higher x86\_64 platform

### 2.2 Recommended requirements

- Processor: Intel® Core<sup>TM</sup> i7, 4 cores (8 logical processors)
- RAM: 16 GB
- Hard disk: 512 GB, SSD
- GPU (optional): NVIDIA® GeForce® GTX 1050 Ti, 4GB GDDR5
- Operating system: Ubuntu 18.04 and higher x86\_64 platform

# 3 Version history

### Version 3.0.2

Released: 2024/01/18

- Updated LPM modules
- Used LPM module: LPM-v7.6-2023-11-10-Ubuntu-18.04-hasp9.0
- Used MMR module: Eyedea-MMR-2.22.0-Ubuntu-18.04-x86\_64-HASP
- Used Sentinel license protection system: aksusbd\_108842-9.12.1
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 3.0.1

Released: 2023/12/07

- Fixed detection angle: license plate detector now returns opposite values to the previous versions; also fixes input for MMR License Plate based
- Updated LPM module: LPM-v7.6-2023-11-10-Ubuntu-18.04-hasp9.0
- Updated MMR module: Eyedea-MMR-2.22.0-Ubuntu-18.04-x86\_64-HASP
- Used Sentinel license protection system: aksusbd\_108842-9.12.1
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 3.0.0

Released: 2023/06/29

- Supported vehicle detection + recognition
- Changed POST endpoint for license plate recognition: recognition → lpRecognition
- Renamed optional license plate recognition data parameters: boundingBox → roi, lpDetection → lpDetections
- Changed default license plate LPM module to 801 (general)
- Moved LPM module and MMR models settings from Dockerfile to env-\*.list files
- Used LPM module: LPM-v7.4.1-2023-01-12-Ubuntu-18.04-hasp
- Used MMR module: Eyedea-MMR-2.21.0-Ubuntu-18.04-x86\_64-HASP
- Updated Sentinel license protection system: aksusbd\_108842-9.12.1
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 2.3.2

Released: 2023/05/23

- Added option to log errors, warnings and recognition statistics to files
- Added server start time to system info response
- Used LPM module: LPM-v7.4.1-2023-01-12-Ubuntu-18.04-hasp
- Used MMR module: Eyedea-MMR-2.20.0-Ubuntu-18.04-x86\_64-HASP
- Updated Sentinel license protection system: aksusbd 108842-8.53.1
- Embedded modules with GPU support are using CUDA 10.0.



(CUDA 10.0 requires the Linux  $x86\_64$  Driver version = 410.48)

### Version 2.3.1

Released: 2023/04/14

- Supported new LPM features: added occlusion, truncated and cluster detection attributes
- Modified layout of Recognition page
- Used LPM module: LPM-v7.4.1-2023-01-12-Ubuntu-18.04-hasp
- Used MMR module: Eyedea-MMR-2.20.0-Ubuntu-18.04-x86\_64-HASP
- Updated Sentinel license protection system: aksusbd-8.51.1
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 2.3.0

Released: 2023/01/05

- Supported new MMR features: added tags to response, all-in-one MMR engine
- Computing all MMR attributes (view, category, make, model, generation, variation, color and tags) by
  default
- Renamed MMR related Dockerfile and env.list variables
- Used LPM module: LPM-v7.4.0-2022-08-30-Ubuntu-18.04-hasp
- Used MMR module: Eyedea-MMR-2.20.0-Ubuntu-18.04-x86\_64-HASP
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 2.2.0

Released: 2022/09/27

- New product branding as "MMR+ANPR REST Server"
- Changed entry point to SERVER\_IP:8080/RESTServer
- Used LPM module: LPM-v7.4.0-2022-08-30-Ubuntu-18.04-hasp
- Used MMR module: Eyedea-MMR-2.12.0-Ubuntu-18.04-x86\_64-HASP
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 2.1.1

Released: 2022/08/18

- Used LPM module: LPM-v7.3.1-2022-08-16-Ubuntu-18.04-hasp
- Used MMR module: Eyedea-MMR-2.12.0-Ubuntu-18.04-x86\_64-HASP
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 2.1.0

Released: 2022/07/28

- Fixed returning error message on SDK (usually license) error.
- Renamed Dockerfile and env.list variables.
- Limited number of LPM Detector CPU threads to 1 (optimized internally).



- · Extended documentation.
- Updated to Java 12. Built with OpenJDK 12.0.1.
- Used LPM module: LPM-v7.3.0-2022-06-22-Ubuntu-18.04-hasp
- Used MMR module: Eyedea-MMR-2.12.0-Ubuntu-18.04-x86\_64-HASP
- Updated Sentinel license protection system: aksusbd-8.41.1
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 2.0.4

Released: 2022/04/11

- Fixed LPM memory leak.
- Used LPM module: LPM-v7.2-2021-10-08-Ubuntu-16.04-hasp
- Used MMR module: Eyedea-MMR-2.11.0-Ubuntu-18.04-x86\_64-HASP
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 2.0.3

Released: 2022/02/24

- Added support for GPU detection (currently available for LPM module 800).
- Reduced Sentinel license requirements.
- Fixed initialization of engines running on the CPU.
- LPM module selection moved to Dockerfile.
- Used LPM module: LPM-v7.2-2021-10-08-Ubuntu-16.04-hasp
- Used MMR module: Eyedea-MMR-2.11.0-Ubuntu-18.04-x86\_64-HASP
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 2.0.2

Released: 2021/12/20

- Split MMR-VCMMGV and MMR-Color in settings, renamed Dockerfile and env.list variables.
- Used LPM module: LPM-v7.2-2021-10-08-Ubuntu-16.04-hasp
- Used MMR module: Eyedea-MMR-2.11.0-Ubuntu-18.04-x86\_64-HASP
- Updated Sentinel license protection system: aksusbd-8.31.1
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 2.0.1

Released: 2021/07/16

- Added generation and variation attributes to MMR result.
- Used LPM module: LPM-v7.1-2020-04-16-Ubuntu-16.04-hasp
- Used MMR module: Eyedea-MMR-2.10.0-Ubuntu-18.04-x86\_64-HASP
- Updated Sentinel license protection system: aksusbd-8.21.1
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)



### Version 2.0.0

Released: 2021/02/02

- Added more detailed SDK information to serverSystemInfo response.
- Removed null / NaN fields from response.
- Used LPM module: LPM-v7.1-2020-04-16-Ubuntu-16.04-hasp
- Used MMR module: Eyedentify-VCL-2.9.0-Ubuntu-16.04-x86\_64-HASP
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 2.0.0-BETA

Released: 2020/12/11

- Used LPM SDK for detection and OCR.
- Added option to specify a bounding box to reduce the input image area scanned by the detector.
- Simplified response for OCR / MMR module disabled (returning null).
- Removed countryID from anprResult response element.
- Used LPM module: LPM-v7.1-2020-04-16-Ubuntu-16.04-hasp
- Used MMR module: Eyedentify-VCL-2.9.0-Ubuntu-16.04-x86\_64-HASP
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 1.2.1

Released: 2020/04/14

- Used EyeScan module: EyeScanSDK-v3.8.3-DummyPack-Ubuntu-16.04-x86\_64-HASP
- Used ANPR module: Eyedentify-ANPR-2.7.0-Ubuntu-16.04-x86\_64-hasp
- Used MMR module: Eyedentify-VCL-2.7.2-Ubuntu-16.04-x86\_64-hasp
- Embedded modules with GPU support are using CUDA 10.0. (CUDA 10.0 requires the Linux x86\_64 Driver version >= 410.48)

### Version 1.2.0

Released: 2019/10/08

- Added support for bypassing the internal detector by specifying license plates positions in JSON format.
- HTML documentation updated.
- Used EyeScan module: EyeScanSDK-v3.7.0-DummyPack-Ubuntu-16.04-x86\_64-HASP
- Used ANPR module: Eyedentify-ANPR-2.5.1-Ubuntu-16.04-x86\_64-hasp
- Used MMR module: Eyedentify-VCL-2.6.0-Ubuntu-16.04-x86\_64-hasp
- Embedded modules with GPU support are using CUDA 9.1.85. (CUDA 9.1.85 requires the Linux x86\_64 Driver version >= 390.46)

### Version 1.1.1

Released: 2019/07/01

- Added option to run the server with ANPR / MMR modules disabled.
- HTML documentation updated.
- Embedded modules with GPU support are using CUDA 9.1.85. (CUDA 9.1.85 requires the Linux x86\_64 Driver version >= 390.46)



### Version 1.1.0

Released: 2019/04/17

- Web interface added: System Info page and Recognition page.
- Updated to the Java 11. Built with OpenJDK 11.0.2.
- HTML documentation added.
- Used EyeScan module: EyeScanSDK-v3.4.1-DummyPack-Ubuntu-16.04-x86\_64-HASP
- Used ANPR module: Eyedentify-ANPR-2.5.1-Ubuntu-16.04-x86\_64-hasp
- Used MMR module: Eyedentify-VCL-2.5.1-Ubuntu-16.04-x86\_64-hasp
- Embedded modules with GPU support are using CUDA 9.1.85. (CUDA 9.1.85 requires the Linux x86\_64 Driver version >= 390.46)

### Version 1.1.0-BETA

Released: 2019/01/11

- Added support for descriptor batch computation.
- Added support for GPU computation (ANPR, MMR).
- Embedded modules with GPU support are using CUDA 9.1.85. (CUDA 9.1.85 requires the Linux x86\_64 Driver version >= 390.46)

### Version 1.0.0

Released: 2018/06/13

- First release version.
- MMR and ANPR recognition REST API server application with basic functionality for still photos.
- Docker image creation scripts included.

# 4 Docker setup

### 4.1 GPU Support Prerequisites

If you do not intend to use the GPU, you can skip this chapter.

### 1. Install GPU

Install GPU supporting NVIDIA CUDA® platform into your Docker host system. The Docker host is the system running the Docker daemon.

### 2. Linux x86\_64

Using the GPU for computation in the Docker environment requires the Docker to be installed and running on the Linux x86\_64 system. Use the distribution which is supported by both the Docker and the NVIDIA Driver.

### 3. Install NVIDIA Driver

Install NVIDIA Driver into the Docker host system. See the Version history for the minimal NVIDIA Driver version required by the CUDA® used in the current build. Write down the version of the NVIDIA Driver you are installing, the same driver version must be installed in the Docker image (see the chapter Building the Docker image).

### 4. Install nvidia-container-runtime library

Install nvidia-container-runtime library into the Docker host system. As a root, run the following script:

./installNvidiaContainerRuntime

# 4.2 Sentinel license protection system

### Installation

The SDK engines used by MMR+ANPR REST Server are protected with a standard third-party software licensing solution, *Sentinel LDK by Gemalto*.

### 1. Install the 32-bit compatibility binaries

As a root, execute the following command to install the 32-bit compatibility binaries:

apt-get install libc6:i386

(Without compatibility binaries error "No such file or directory." might appear.)

### 2. Uncompress the package containing the Run-time Environment installer

Uncompress the aksusbd\*.tar.gz file.

### 3. Uninstall prior Sentinel LDK Run-time Environment version

If you have installed a prior version of the Sentinel LDK Run-time Environment, as a root, run the following script from the uncompressed directory to uninstall it:

/dunst

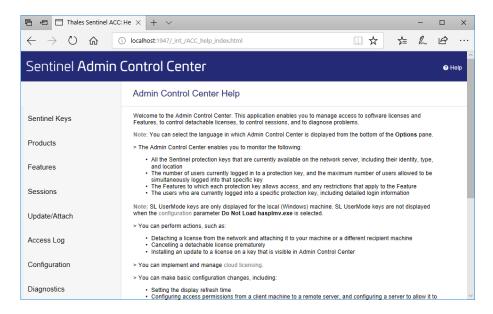
### 4. Install the Sentinel LDK Run-time Environment

As a root, run the following script from the uncompressed directory to install the Sentinel LDK Runtime Environment:

./dinst

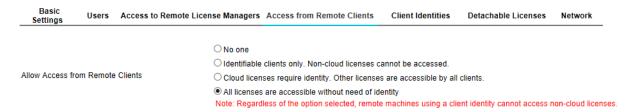
### Verification

After the successful Sentinel License Server installation, open the address <a href="http://localhost:1947">http://localhost:1947</a> in a web browser and check whether the license server is running. If the Sentinel Admin Control Center web application is displayed, the license server is running. License server can be configured to allow to connect clients to use available licenses (configured as a server) or it can connect to another license server (configured as a client).



### Server configuration

To set the license server as a license provider, please open the address in your web browser <a href="http://localhost:1947/">http://localhost:1947/</a> int /config from.html and choose the appropriate option from Allow Access from Remote Clients to allow other clients to connect to the network license key plugged in the server.



### Client configuration

To set the license server as a client, open the address <a href="http://localhost:1947/\_int\_/config\_to.html">http://localhost:1947/\_int\_/config\_to.html</a> in a web browser and choose the Allow Access to Remote Licenses option. If the license provider is in another network than the computer, put the server's IP address into the field Remote License Search Parameters.



Basic Settings	Users	Access t	o Remote Licens	e Managers	Access from Remote Clients	Client Identities	Detachable Licenses	Network
Allow Access to	Remote Li	censes	<u> </u>	You may	experience a delay of a few minu	ites before your change	es take effect.	
Broadcast Searc	ch for Rem	ote License	s 🗹	]				
Aggressive Sea	rch for Ren	note Licens	es [	]				
Remote License	Search Pa	arameters	Γ					

# 4.3 Building the Docker image

### 0. Prerequisites

Docker (<a href="https://www.docker.com">https://www.docker.com</a>) must be installed and Docker daemon must be running before creating the Docker image.

### 1. Set the Docker image variables (Dockerfile)

Instructions for building the Docker image are listed in Dockerfile which is located in the [PACKAGE]/ directory. Set the NVIDIA\_DRIVER\_VERSION variable (line 14) to install the proper version of the NVIDIA Driver (needed for GPU computation). The same version of the Driver must be installed on the Docker host system.

The NVIDIA Driver version may be found out by running the following command:

Set the NVIDIA\_DRIVER\_VERSION variable to empty to disable the NVIDIA Driver installation. In that case only CPU computation will be supported.

Example of line 14 in Dockerfile which enables GPU computation:

ENV NVIDIA\_DRIVER\_VERSION=410.104

Example of line 14 in Dockerfile for CPU computation only:

ENV NVIDIA\_DRIVER\_VERSION=

To update LPM or MMR SDK, change the LPM\_VERSION (line 17) or MMR\_VERSION (line 20) variables, respectively. The appropriate \*.tar.gz archive must be in the [PACKAGE]/ directory.

Example of line 17 in Dockerfile defining the latest LPM SDK version:

ENV LPM\_VERSION=v7.6-2023-11-10-Ubuntu-18.04-hasp9.0

Example of line 20 in Dockerfile defining the latest Eyedea MMR SDK version:

ENV MMR\_VERSION=2.22.0-Ubuntu-18.04-x86\_64-HASP

### 2. Run the build script (buildDocker)

Use the buildDocker script located in the [PACKAGE]/ directory to build the Docker image:

./buildDocker

The Docker image is built using the following command:

docker build -t mmr-anpr-rest-server .

The -t option specifies the name of the new Docker image.



# 4.4 Running the Docker image

### 1. Set the application variables (env-GPU.list or env-CPU.list)

The application settings (license server address, number of threads, ...) are loaded from the system environment variables by the application. The supported variables are defined in the env-GPU.list and env-CPU.list files (the first one is intended to use the GPU for computation, the other uses the CPU). One of these files is passed to the Docker during the image initialization and its variables are available in the Docker container as system environment variables.

In the following overview, <ENGINE> stands for: LPM\_LP\_DETECTOR, LPM\_LP\_OCR, MMR\_LP, LPM\_BOX\_DETECTOR and MMR\_BOX.

HASP_REMOTE_SERVERADDR	The address of the Sentinel License Manager server with the valid license. If the licenses are on the Docker host, you can usually set the IP address to 10.0.75.1 or 172.17.0.1.
LPM_LP_MODULE_ID	The three-digit identifiers of LPM modules used for the license plate detection + OCR and the box detection, respectively. The appropriate
LPM_BOX_MODULE_ID	*.tar.gz archives must be in the [PACKAGE]/LPM-modules directory.  Currently, only LPM module 802 supports the box detection.
MMR_LP_MODEL	Specify the binary models used for license plate based (MMR_*) and box based (MMRBOX_*) MMR, respectively. The default MMR models are *_VCMMGVCT_* which recognize view, category, make, model, generation, variation, color and tags. If you do not have licenses for all
MMR_BOX_MODEL	these features or prefer fast versions (instead of default precise ones), select the appropriate data models from the [PACKAGE]/Eyedea-MMR-\${MMR_VERSION}.tar.gz/\${MMR_PATH}/model directory. See the MMR documentation for details.
<engine>_NUMTHREADS</engine>	The number of engine's threads to initialize. Set the variable to 0 to disable the given engine. Set -1 to select the number of threads automatically (1 for CPU, or 1 for each <engine>_GPU_ID in case of GPU computation mode).  Note: When running on CPU, the number of LPM Detector threads is</engine>
	limited to 1 because it internally uses the optimal number of CPU threads.
<engine>_COMPUTATION_MODE</engine>	Specifies whether the given engine runs on CPU, or GPU. (Certain older LPM Detectors may support only CPU.)
<engine>_GPU_ID</engine>	Relevant only for GPU computation. Specifies the 0-based index or indexes of GPU devices to compute on. If more GPUs are available, you can assign a comma separated list of indexes to a single engine (e.g.: MMR_BOX_GPU_ID=0,1), or distribute them among multiple engines (e.g.: LPM_LP_OCR_GPU_ID=0 MMR_LP_GPU_ID=1).
LOG_STATS_PERIOD_REQUEST	Specifies whether and, if necessary, with what period recognition statistics should be logged to a file. Set a positive integer <i>N</i> to log recognition statistics to a new file every <i>N</i> -th request, or 0 to disable recognition statistics logging.  See Log files chapter for details.
LOG_ERRORS	Specifies whether to log errors to a file. Set 1 to enable, or 0 to disable errors and warnings logging. See Log files chapter for details.

Check the SDK Engine Overview chapter to select the appropriate SDK engines for your use case.

### Example:

Let's have the env-GPU.list file with the following configuration (only the relevant variables listed for brevity):

```
HASP REMOTE SERVERADDR=172.17.0.1
LPM LP MODULE ID=800
LPM LP DETECTOR NUMTHREADS=1
LPM LP DETECTOR COMPUTATION MODE=GPU
LPM LP DETECTOR GPU ID=0
LPM_LP_OCR_NUMTHREADS=1
LPM LP OCR COMPUTATION MODE=GPU
LPM LP OCR GPU ID=0
LPM BOX DETECTOR NUMTHREADS=0
MMR LP MODEL=MMR VCCT FAST 2023Q4.dat
MMR_LP_NUMTHREADS=1
MMR LP COMPUTATION MODE=GPU
MMR LP GPU ID=0
MMR BOX NUMTHREADS=0
LOG STATS PERIOD REQUEST=1000
LOG_ERRORS=1
```

The license key with the valid licenses must be plugged into the current machine.

There will be three running SDK engines: LPM License Plate Detector, LPM OCR and License Plate based MMR, each of them running in one thread on the GPU. The Box engines will be disabled.

LPM License Plate Detector + OCR will use the European module 800; the MMR will use the fast model to recognize only view, category, color and tags.

Recognition statistics will be saved to a file after every 1000th recognition request is processed. Any error and warning occurrences will be saved to files, too.

### 2. Run the image (runDockerGPU or runDockerCPU)

Use the runDockerGPU or runDockerCPU script located in the [PACKAGE]/ directory to run the built Docker image with / without the support for GPU computation. Edit these scripts if needed.

```
runDockerGPU – support for GPU computation:

docker run --gpus device=0 --env-file env-GPU.list -p 8080:8080 mmr-anpr-
rest-server

runDockerCPU – CPU computation only:

docker run --env-file env-CPU.list -p 8080:8080 mmr-anpr-rest-server

Notes:

The --env-file option specifies the file with the environment variables.

The -p option publishes port 8080 in the container and maps it to the host's port 8080.

The --gpus option specifies GPU device(s) used by the container. Possibilities:

• Use a GPU device using its index: --gpus device=0

• Use multiple GPU devices using their indexes: --gpus "device=2,3"

• Use all available GPU devices: --gpus all
```

The server tries to initialize all engine instances specified in the env-\*.list file. Check the error output for details if there are problems starting any engine. After launching the Docker container, the application is accessible at:

http://[MACHINE IP]:8080/RESTServer/

You can check the status of the engines on the application home page or by requesting the serverSystemInfo. "DISABLED" means that no thread was requested for the given engine, "FAILED TO START" means that all requested threads of the given engine could not be started; in both cases, the server handles requests and returns data obtained by other running engines.

The engine status never changes when the container is started. If an engine encounters a license problem after the successful initialization, its status will still be "RUNNING", but the response to a request for that engine will have a status code of 500 with a message indicating the problematic engine (e.g.: "Error during OCR processing. Computation error. Please check your licenses.").

### 4.5 Log files

There is a possibility to enable logging of recognition statistics and errors in order to regularly monitor the server usage and report problems. Logging can be enabled by setting the corresponding variable in the env-\*.list file.

If enabled, each statistics record or problem produces a new file <Type>\_<year>-<month>-<day>\_<hour>-<minute>-<second>-<millisecond>.log in the Docker container's /usr/local/tomcat/webapps/RESTServer\_data/logs/ folder.

### Log file name

The following table lists possible values of <Type> in the log file name:

Type	Description
Stats	Recognition statistics.
BadRequest 400 Bad Request response status code is returned.  ErrorResponse 500 Internal Server Error response status code is returned.	
RuntimeWarning	Less serious problem during server startup or recognition processing.

### **Recognition statistics**

Recognition statistics log files contain a JSON object which contains the following items:

Response item Description		Data type
requestTimestamp	Date and time of the user request with a millisecond precision.	String
responseTimestamp	Date and time of the server response with a millisecond precision.	String
serverStartedTimestamp	Date and time when the server started with a millisecond precision.	String
totalTaskCount	Number of user recognition requests (including erroneous).	Integer
totalDetectionCount	Number of processed detection computation tasks.	Integer
totalOcrCount	Number of processed OCR computation tasks.	Integer



totalMmrCount	Number of processed MMR computation tasks.	Integer
---------------	--	---------

### **Errors**

Error log files contain a text message describing the problem.

### **Notes**

To run the Docker container with a <u>volume</u> to store log files on the host, add -v \$PWD/logs:/usr/local/tomcat/webapps/RESTServer\_data/logs to the runDocker\* script.

The time zone used for date and time associated with log files depends on the Docker container locale, which is UTC by default. To use the host time zone instead, add -v/etc/timezone:/etc/timezone:ro to the runDocker\* script.



# 5 REST API Documentation

### 5.1 SDK Engine Overview

Which SDK engines do you need? Check the following table.

Use Case	SDK Engines
License plate detection	LPM License Plate Detector
License plate detection + OCR	LPM License Plate Detector, LPM OCR
License plate detection + OCR + Vehicle recognition	LPM License Plate Detector, LPM OCR, MMR License Plate based
Vehicle detection	LPM Box Detector
Vehicle detection + Vehicle recognition	LPM Box Detector, MMR Box based
Vehicle recognition (without detection; detections must be provided in the request)	MMR License Plate based, or MMR Box based

*Note:* License plate detection + OCR = ANPR

LPM License Plate Detector detects license plates.

**LPM OCR** recognizes the text and type of license plates detected by LPM License Plate Detector.

**MMR License Plate based** can recognize the view, category, make, model, generation, variation, color and tags of vehicles specified by their license plate. Either LPM License Plate Detector and LPM OCR are needed, or the license plate detections must be provided in the request.

LPM Box Detector detects vehicles (and some other "road users" like pedestrians, kickbikes, etc.).

**MMR Box based** recognizes the view, category, make, model, generation, variation, color and tags of vehicles (or "road users") specified by their bounding box. Either LPM Box Detector is needed, or the box detections must be provided in the request.

# 5.2 Response Status Codes

The following table lists all response status codes MMR+ANPR REST Server returns.

Status Code	Meaning
200	Success.
400	Bad Request. The request was invalid. The error message provides the details.
500	Internal Server Error. Most of these errors are caused by a licensing issue. The error message provides the details.

# 5.3 Entry point

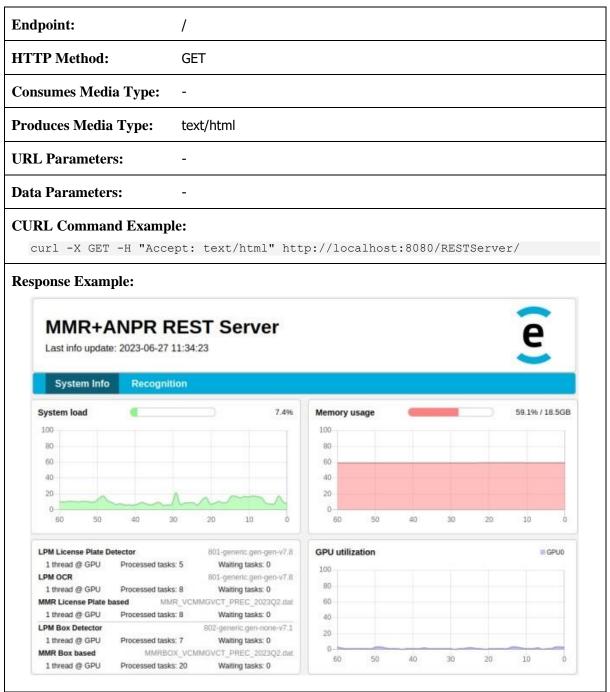
SERVER IP:8080/RESTServer



# 5.4 System Info

System info contains information about system resources and SDK engines.

# Main web page with real time server monitoring



### Text output with server monitoring information

Endpoint:	1
HTTP Method:	GET
Consumes Media Type:	-

Produces Media Type: text/plain

URL Parameters: 
Data Parameters: -

### **CURL Command Example:**

curl -X GET -H "Accept: text/plain" http://localhost:8080/RESTServer/

### **Response Example:**

```
System:
- Average load: 9.93%
 - Used memory: 58.99% (18.48 GB)
 - Started on: 2023-06-27 09:26:44
GPU 0 (Graphics Device):
 - Utilization: 6%
 - Free memory: 3455 / 5905 MB
Detection:
- Engine: LPM License Plate Detector
 - Version: v7.4.1-2023-01-12-Ubuntu-18.04-hasp
 - Module ID: 801
 - Module version: 801-generic.gen-gen-v7.8
 - Computation mode: GPU
 - Status: RUNNING
 - Processing batch size: 1
 - Number of running threads: 1
 - Number of waiting tasks: 0
 - Number of processed tasks: 5
Classification:
 - Engine: LPM OCR
 - Version: v7.4.1-2023-01-12-Ubuntu-18.04-hasp
 - Module ID: 801
 - Module version: 801-generic.gen-gen-v7.8
 - Computation mode: GPU
 - Status: RUNNING
 - Processing batch size: 1
 - Number of running threads: 1
 - Number of waiting tasks: 0
 - Number of processed tasks: 8
Classification:
- Engine: MMR License Plate based
 - Version: 2.21.0-Ubuntu-18.04-x86 64-HASP
 - Module: MMR VCMMGVCT PREC 2023Q2.dat
 - Module version: 2023\overline{0}512
 - Computation mode: GPU
 - Status: RUNNING
 - Processing batch size: 1
 - Number of running threads: 1
 - Number of waiting tasks: 0
 - Number of processed tasks: 8
Detection:
 - Engine: LPM Box Detector
 - Version: v7.4.1-2023-01-12-Ubuntu-18.04-hasp
 - Module ID: 802
 - Module version: 802-generic.gen-none-v7.1
 - Computation mode: GPU
 - Status: RUNNING
 - Processing batch size: 1
 - Number of running threads: 1
```

```
- Number of waiting tasks: 0
- Number of processed tasks: 7

Classification:
- Engine: MMR Box based
- Version: 2.21.0-Ubuntu-18.04-x86_64-HASP
- Module: MMRBOX_VCMMGVCT_PREC_2023Q2.dat
- Module version: 20230513
- Computation mode: GPU
- Status: RUNNING
- Processing batch size: 1
- Number of running threads: 1
- Number of waiting tasks: 0
- Number of processed tasks: 20
```

### Get detailed server system info

Endpoint: /serverSystemInfo

HTTP Method: GET

Consumes Media Type: 
Produces Media Type: application/json

URL Parameters: 
Data Parameters: -

#### **CURL Command Example:**

curl -X GET http://localhost:8080/RESTServer/serverSystemInfo

### **Response Example:**

```
"timestamp": 1687858635246,
"serverStartedTimestamp": 1687858004078,
"systemLoadAverage": 11.363636363636363,
"systemUsedMemory": 58.99442995234615,
"systemUsedMemoryBytes": 19843907584,
"processingServersInfosList": [
    "batchSize": 1,
    "computationMode": "GPU",
    "engineName": "LPM",
    "engineType": "License Plate Detector",
    "engineVersion": "v7.4.1-2023-01-12-Ubuntu-18.04-hasp",
    "moduleId": 801,
    "moduleVersion": "801-generic.gen-gen-v7.8",
    "numComputingThreads": 1,
    "numProcessedTasks": 5,
    "numWaitingTasks": 0,
    "status": "RUNNING"
  },
  {
    "batchSize": 1,
    "computationMode": "GPU",
    "engineName": "LPM",
    "engineType": "OCR",
    "engineVersion": "v7.4.1-2023-01-12-Ubuntu-18.04-hasp",
    "moduleId": 801,
    "moduleVersion": "801-generic.gen-gen-v7.8",
```



```
"numComputingThreads": 1,
      "numProcessedTasks": 8,
      "numWaitingTasks": 0,
      "status": "RUNNING"
      "batchSize": 1,
      "computationMode": "GPU",
      "engineName": "MMR",
      "engineType": "License Plate based",
      "engineVersion": "2.21.0-Ubuntu-18.04-x86 64-HASP",
      "moduleName": "MMR_VCMMGVCT_PREC_2023Q2.dat",
      "moduleVersion": "20230512",
      "numComputingThreads": 1,
      "numProcessedTasks": 8,
      "numWaitingTasks": 0,
      "status": "RUNNING"
    },
      "batchSize": 1,
      "computationMode": "GPU",
      "engineName": "LPM",
      "engineType": "Box Detector",
      "engineVersion": "v7.4.1-2023-01-12-Ubuntu-18.04-hasp",
      "moduleId": 802,
      "moduleVersion": "802-generic.gen-none-v7.1",
      "numComputingThreads": 1,
      "numProcessedTasks": 7,
      "numWaitingTasks": 0,
      "status": "RUNNING"
    },
    {
      "batchSize": 1,
      "computationMode": "GPU",
      "engineName": "MMR",
      "engineType": "Box based",
      "engineVersion": "2.21.0-Ubuntu-18.04-x86 64-HASP",
      "moduleName": "MMRBOX VCMMGVCT PREC 2023Q2.dat",
      "moduleVersion": "20230513",
      "numComputingThreads": 1,
      "numProcessedTasks": 20,
      "numWaitingTasks": 0,
      "status": "RUNNING"
   }
  ],
  "gpuInfoList": [
      "id": 0,
"name": "Graphics Device",
      "totalMemoryMB": 5905,
      "freeMemoryMB": 3455,
      "gpuUtilizationPerc": 6
  ]
}
```

### **Response Definitions:**

The following table describes each item in the response.

Response item	Description	Data type
timestamp	Current system time in milliseconds.	Integer
serverStartedTimestamp	System time in milliseconds when the server started.	Integer



systemLoadAverage	Recent CPU usage for the whole system in percent.	Decimal number
systemUsedMemory	Amount of physical memory used by any process in percent.	Decimal number
systemUsedMemoryBytes	Amount of physical memory used by any process in bytes.	Integer
processingServersInfosList	Information about the SDK engines.	Array of objects
processingServersInfosList/ batchSize	Size of the computation batch.	Integer
processingServersInfosList/ computationMode	Type of processing unit used for computation. Either "CPU", or "GPU".	String
processingServersInfosList/ engineName	SDK engine name.	String
processingServersInfosList/ engineType	SDK engine type.	String
processingServersInfosList/ engineVersion	SDK engine version.	String
processingServersInfosList/ moduleId	DK engine module ID.	Integer
processingServersInfosList/ moduleName	SDK engine module name.	String
processingServersInfosList/ moduleVersion	SDK engine module version.	String
processingServersInfosList/ numComputingThreads	Number of initialized engine's threads.	Integer
processingServersInfosList/ numProcessedTasks	Number of processed computation tasks.	Integer
processingServersInfosList/ numWaitingTasks	Number of queued computation tasks to be processed.	Integer
processingServersInfosList/ status	SDK engine status. Either "RUNNING" (at least 1 thread successfully initialized), "DISABLED" (no thread requested), or "FAILED TO START" (all requested threads could not be started).	String
gpuInfoList	Information about available GPU devices.	Array of objects
gpuInfoList/ <b>id</b>	GPU device ID.	Integer
gpuInfoList/name	GPU device name.	String
gpuInfoList/totalMemoryMB	Total amount of physical GPU device memory in megabytes.	Integer



gpuInfoList/freeMemoryMB	Amount of free physical GPU device memory in megabytes.	Integer	
gpuInfoList/gpuUtilizationPerc	Utilization of the GPU device in percent.	Integer	

# 5.5 Recognition

Recognition provides information about recognized license plates and corresponding vehicles in the input image.

# Web page with image upload and recognition functionality using the license plate, or box detector

Endpoint:	/recognition	
HTTP Method:	GET	
Consumes Media Type:	-	
Produces Media Type:	text/html	
URL Parameters:	-	
Data Parameters:	-	
CURL Command Example:		
<pre>curl -X GET http://localhost:8080/RESTServer/recognition</pre>		

# Response Examples:

Using license plate detector:





### Using box detector:



### **Notes:**

License plate detector, LPM OCR and license plate based MMR engines must be running for both ANPR and MMR results to be displayed.

When the Box detector is used, only MMR results are displayed (for LPM box detector and box based MMR engines running).

Occluded attribute is based on the value of **lpDetection/occlusion**: if occlusion is greater or equal to 0.25, the license plate is considered to be occluded (marked with a green  $\checkmark$ ); otherwise it is considered to be not occluded (marked with a red X).

The score of an MMR tag is displayed as a tooltip when you hover the mouse cursor over it.

# Detect and read license plates in the input image and recognize the corresponding vehicles

Endpoint:	/lpRecognition
HTTP Method:	POST
Consumes Media Type:	multipart/form-data
Produces Media Type:	application/json
URL Parameters:	-

### **Data Parameters:**

file – form data parameter containing input image

roi - (optional) form data parameter containing a JSON object that defines the area of the input image to be scanned by the detector



The region of interest parameter is defined by its corners coordinates: topLeftX, topLeftY, topRightX, topRightY, bottomLeftX, bottomLeftY, bottomRightX and bottomRightY (decimal numbers).

### Example:

```
{
  "topLeftX": 176,
  "topLeftY": 362,
  "topRightX": 1234,
  "topRightY": 362,
  "bottomLeftX": 176,
  "bottomLeftY": 1000,
  "bottomRightX": 1234,
  "bottomRightY": 1000
}
```

For the sides of a region of interest parallel to the sides of the image, a simplified form of *roi* defined by its sides can be used instead: leftX, topY, rightX and bottomY (decimal numbers).

### Example:

```
{
  "leftx": 176,
  "topY": 362,
  "rightx": 1234,
  "bottomY": 1000
}
```

lpDetections – (optional) form data parameter containing a JSON object with an array of license plate positions (for MMR computation only)

The license plate detections parameter is defined as an array of "center, angle, scalePPM" structures which define the position of a license plate in the image for MMR computation. If this parameter is used, ANPR (automatic detection and OCR) will not run during the input image processing.

center -2D point (structure of x and y decimal numbers) defining the center of the license plate. The *center* point must be inside the input image.

angle – Clockwise correction of the source image in degrees (decimal number).

scalePPM – The real-world scale in pixels per meter of the input image in the *center* position (decimal number). The *scalePPM* defines the real size of the license plate in the image and does not consider the margin added by the detector.

#### Example:

### **CURL Command Examples:**

### Use automatic detection:

```
curl -X POST \
    -H "Content-Type: multipart/form-data" \
    -F "file=@image.jpg" \
```

http://localhost:8080/RESTServer/lpRecognition

### Use automatic detection with a region of interest in JSON file:

```
curl -X POST \
    -H "Content-Type: multipart/form-data" \
    -F "file=@image.jpg" \
    -F "roi=@roi.json" \
    http://localhost:8080/RESTServer/lpRecognition
```

### Use automatic detection with a region of interest in JSON string:

```
curl -X POST \
    -H "Content-Type: multipart/form-data" \
    -F "file=@image.jpg" \
    -F "roi={\"topLeftX\":176,\"topLeftY\":362,\"topRightX\":1234,
\"topRightY\":362,\"bottomLeftX\":176,\"bottomLeftY\":1000,
\"bottomRightX\":1234,\"bottomRightY\":1000}" \
    http://localhost:8080/RESTServer/lpRecognition
```

### Use automatic detection with a simplified form of region of interest in JSON string:

```
curl -X POST \
    -H "Content-Type: multipart/form-data" \
    -F "file=@image.jpg" \
    -F "roi={\"leftX\":176,\"topY\":362,\"rightX\":1234,\"bottomY\":1000}"
    http://localhost:8080/RESTServer/lpRecognition
```

#### **Detections in JSON file:**

```
curl -X POST \
   -H "Content-Type: multipart/form-data" \
   -F "file=@image.jpg" \
   -F "lpDetections=@detections.json" \
   http://localhost:8080/RESTServer/lpRecognition
```

### **Detections in JSON string:**

```
curl -X POST \
    -H "Content-Type: multipart/form-data" \
    -F "file=@image.jpg" \
    -F "lpDetections=[{\"center\":{\"x\":176.5,\"y\":362.0},\"angle\":-5.1,
\"scalePPM\":214.3}]" \
    http://localhost:8080/RESTServer/lpRecognition
```

#### **Notes:**

Content type of the request is **multipart/form-data**, where the inputs are stored in the form data fields.

Input image is referenced with filepath (starting with @) in the form field **file**.

Optional parameters **roi** and **lpDetections** can be referenced with filepath (starting with @, referencing a text file containing JSON string) or can contain the whole JSON as a string (special characters must be escaped).

### **Response Examples:**

Automatic license plate detection, OCR and vehicle recognition:

```
"x": 1181.4339599609375,
      "y": 879.98583984375
    },
      "x": 1184.06640625,
      "y": 56.4561767578125
      "x": 819.875,
      "y": 968.9932861328125
  ],
  "width": 364.40714,
  "height": 76.51563,
  "angles": [ -1.9716004, 0.0, 0.0 ],
  "score": 0.9058307,
  "occlusion": 0.0011757431,
  "position": {
    "center": {
     "x": 1000.6544799804688,
      "y": 700.78296
    "angle": 1.9716004,
    "scalePPM": 700.78296
 }
"anprResult": {
 "country": "N",
 "countryScore": 0.99532324,
 "ocrText": "CV50070",
 "ocrTextScore": 0.9993771
"mmrResult": {
 "view": "frontal",
  "viewID": 1,
 "viewScore": 0.9999852,
  "category": "CAR",
  "categoryID": 2,
  "categoryScore": 0.99994755,
  "make": "VW",
 "makeID": 43,
  "makeScore": 0.999934,
  "model": "Passat",
  "modelID": 3569,
  "modelScore": 0.9994862,
  "generation": "Mk VI (2005)",
  "generationID": 3691,
  "generationScore": 0.9979515,
  "color": "WHITE",
  "colorID": 13,
  "colorScore": 0.73097533,
  "tags": [
      "name": "caravan",
      "value": "no",
      "id": 2,
      "score": 0.99945587
      "name": "law_enforcement",
"value": "yes",
      "id": 3,
      "score": 1.0
    },
     "name": "ambulance",
"value": "no",
```

```
"id": 6,
    "score": 0.999996

},

{
    "name": "fire_brigade",
    "value": "no",
    "id": 8,
    "score": 0.9999945
},

{
    "name": "push_bumper",
    "value": "no",
    "id": 28,
    "score": 0.99893206
}

}

]
}
}
```

### License plate detection provided in the request:

```
"lpDetection": {
  "angles": [ -1.9716004, 0.0, 0.0 ],
  "position": {
    "center": {
     "x": 1000.6544799804688,
      "y": 700.78296
    "angle": 1.9716004,
    "scalePPM": 700.78296
 }
"mmrResult":{
 "view": "frontal",
  "viewID": 1,
  "viewScore": 0.9999852,
 "category": "CAR",
 "categoryID": 2,
  "categoryScore": 0.99994755,
  "make": "VW",
  "makeID": 43,
  "makeScore": 0.999934,
  "model": "Passat",
  "modelID": 3569,
  "modelScore": 0.9994862,
  "generation": "Mk VI (2005)",
  "generationID": 3691,
  "generationScore": 0.9979515,
  "color": "WHITE",
  "colorID": 13,
  "colorScore": 0.73097533,
  "tags": [
   {
     "name": "caravan",
     "value": "no",
     "id": 2,
      "score": 0.99945587
    },
      "name": "law_enforcement",
     "value": "yes",
     "id": 3,
      "score": 1.0
    },
```

```
"name": "ambulance",
    "value": "no",
    "id": 6,
    "score": 0.999996
},
{
    "name": "fire_brigade",
    "value": "no",
    "id": 8,
    "score": 0.9999945
},
{
    "name": "push_bumper",
    "value": "no",
    "id": 28,
    "score": 0.99893206
}
}
]
}
```

### **Notes:**

When the **lpDetections** form field is provided in the request, the response does **not** contain the **anprResult** element and **lpDetection** element contains only the fields from the request.

If the **LPM License Plate Detector** engine is not running and the **lpDetections** form field is not provided in the request, an empty array is returned in the response.

The **anprResult** element is returned in the response only if the **LPM License Plate Detector** and the **LPM OCR** engines are running and the **lpDetections** form field is **not** provided in the request.

To obtain the **mmrResult** element in the response, running the **MMR License Plate based** engine is required. Additionally, either the **LPM License Plate Detector** and the **LPM OCR** engines must be running, or the **lpDetections** form field must be provided in the request.

### **Response Definitions:**

The following table describes each item in the response.

Response item	Description	Data type
IpDetection	Information about the detected license plate location in the input image.	Object
IpDetection/corners	An array of top-left, top-right, bottom-right and bottom-left corners of the detected license plate.	Array of objects
IpDetection/corners/x	The horizontal coordinate of the license plate corner within the image.	Decimal number
IpDetection/corners/y	The vertical coordinate of the license plate corner within the image.	Decimal number
IpDetection/width	The width of the detected license plate in pixels.	Decimal number
IpDetection/height	The height of the detected license plate in pixels.	Decimal number



IpDetection/angles	The license plate orientation - roll, pitch, yaw angles in degrees (clockwise). Currently, only the first array item, roll, is evaluated.	Array of decimal numbers
IpDetection/score	The license plate detection confidence factor. Range $0-1$ .	Decimal number
IpDetection/occlusion	Specifies how much the detection is occluded. Range 0 (not occluded) – 1 (fully occluded).	Decimal number
IpDetection/truncated	Specifies whether the detection is truncated (the bounding box does not cover the whole object).	Boolean
lpDetection/clusterID	ID of a cluster, to which this detection belongs. Not yet implemented in the current LPM modules.	Integer
IpDetection/clusterScore	Confidence factor for clusterID prediction. Range $0-1$ .	Decimal number
IpDetection/position	The "center, angle, scalePPM" structure defining the license plate position in the image for MMR computation.	Object
IpDetection/position/center	The coordinates of the license plate center within the image.	Object
IpDetection/position/center/x	The horizontal coordinate of the license plate center within the image.	Decimal number
IpDetection/position/center/y	The vertical coordinate of the license plate center within the image.	Decimal number
IpDetection/position/angle	Clockwise correction of the source image in degrees.	Decimal number
IpDetection/position/scalePPM	The real-world scale in pixels per meter of the image in the center position. The scalePPM defines the real size of the license plate in the image and does not consider the margin added by the detector.	Decimal number
	The value is calculated by the LPM OCR engine.	
anprResult	Information about the recognized license plate.	Object
anprResult/country	The international license plate country code. If the value is "UNK", then it was recognized as a false positive detection.	String
anprResult/countryScore	The confidence factor for "country" prediction. Range $0-1$ .	Decimal number
anprResult/ocrText	The license plate text recognized by the OCR.	String
anprResult/ocrTextScore	The confidence factor for the OCR result. Range $0-1$ .	Decimal number
mmrResult	Information about the recognized vehicle attributes.	Object
mmrResult/ <b>view</b>	The recognized vehicle view, either "FRONTAL", or "REAR".	String



mmrResult/viewID	ID of the recognized vehicle view.	Integer
mmrResult/viewScore	The confidence factor for the view result. Range $0-1$ .	Decimal number
mmrResult/category	The recognized vehicle category, e.g., "BUS", "CAR", "HVT", For the full list of possible categories and their definition, check the Eyedea MMR SDK documentation.	String
mmrResult/categoryID	ID of the recognized vehicle category.	Integer
mmrResult/categoryScore	The confidence factor for the category result. Range $0-1$ .	Decimal number
mmrResult/ <b>make</b>	The recognized vehicle manufacturer, e.g., "VW", "Ford", "Fiat", For the full list of possible categories, check the Eyedea MMR SDK documentation.	String
mmrResult/makeID	ID of the recognized vehicle manufacturer.	Integer
mmrResult/makeScore	The confidence factor for the make result. Range $0-1$ .	Decimal number
mmrResult/ <b>model</b>	The recognized vehicle model (vehicle instance defined by a bodywork), e.g., "Golf", "Mondeo", "500",	String
mmrResult/modelID	ID of the recognized vehicle model.	Integer
mmrResult/modelScore	The confidence factor for the model result. Range $0-1$ .	Decimal number
mmrResult/generation	The recognized vehicle generation (vehicle mark and first model year), e.g., "Mk VI (2019)", "Mk I (2020)",	String
mmrResult/generationID	ID of the recognized vehicle generation.	Integer
mmrResult/generationScore	The confidence factor for the generation result. Range $0-1$ .	Decimal number
mmrResult/variation	The recognized vehicle variation (vehicle trim level and/or body type), e.g., "AMG", "AMG-Line SUV", "Coupe",	String
mmrResult/variationID	ID of the recognized vehicle variation.	Integer
mmrResult/variationScore	The confidence factor for the variation result. Range $0-1$ .	Decimal number
mmrResult/color	The recognized vehicle color, e.g., "BLUE", "GRAY", "RED",	String
mmrResult/colorID	ID of the recognized vehicle color.	Integer
mmrResult/colorScore	The confidence factor for the color result. Range $0-1$ .	Decimal number
mmrResult/tags	An array of recognized vehicle traits.	Array of objects



mmrResult/tags/ <b>name</b>	The name of the trait, e.g., "caravan", "ambulance", For the full list of possible tags and their definition, check the Eyedea MMR SDK documentation.	String
mmrResult/tags/value	The value of the trait. Either "yes", or "no".	String
mmrResult/tags/id	ID of the trait value.	Integer
mmrResult/tags/score	The confidence factor for the tag value. Range $0-1$ .	Decimal number

### Detect and recognize vehicles (or "road users") in the input image

Endpoint:	/boxRecognition
HTTP Method:	POST
Consumes Media Type:	multipart/form-data
Produces Media Type:	application/json
URL Parameters:	-

### **Data Parameters:**

file – form data parameter containing input image

roi - (optional) form data parameter containing a JSON object that defines the area of the input image to be scanned by the detector

The region of interest parameter is defined by its corners coordinates: topLeftX, topLeftY, topRightX, topRightY, bottomLeftX, bottomLeftY, bottomRightX and bottomRightY (decimal numbers).

### Example:

```
{
  "topLeftX": 176,
  "topLeftY": 362,
  "topRightX": 1234,
  "topRightY": 362,
  "bottomLeftX": 176,
  "bottomLeftY": 1000,
  "bottomRightX": 1234,
  "bottomRightY": 1000
}
```

For the sides of a region of interest parallel to the sides of the image, a simplified form of *roi* defined by its sides can be used instead: leftX, topY, rightX and bottomY (decimal numbers).

### Example:

```
{
  "leftX": 176,
  "topY": 362,
  "rightX": 1234,
  "bottomY": 1000
}
```

boxDetections – (optional) form data parameter containing a JSON object with an array of (vehicle) bounding box corners



The box detections parameter is defined as an array of vehicle's top-left and bottom-right corners coordinates: topLeftX, topLeftY, bottomRightX and bottomRightY (decimal numbers).

### Example:

```
[
    "topLeftX": 225,
    "topLeftY": 469,
    "bottomRightX": 1454,
    "bottomRightY": 1042
},
....
]
```

### **CURL Command Examples:**

#### Use automatic detection:

```
curl -X POST \
    -H "Content-Type: multipart/form-data" \
    -F "file=@image.jpg" \
    http://localhost:8080/RESTServer/boxRecognition
```

### Use automatic detection with a simplified form of region of interest in JSON string:

```
curl -X POST \
    -H "Content-Type: multipart/form-data" \
    -F "file=@image.jpg" \
    -F "roi={\"leftX\":176,\"topY\":362,\"rightX\":1234,\"bottomY\":1000}"
    http://localhost:8080/RESTServer/boxRecognition
```

#### **Box detections in JSON file:**

```
curl -X POST \
   -H "Content-Type: multipart/form-data" \
   -F "file=@image.jpg" \
   -F "boxDetections=@detections.json" \
   http://localhost:8080/RESTServer/boxRecognition
```

### **Box detections in JSON string:**

```
curl -X POST \
    -H "Content-Type: multipart/form-data" \
    -F "file=@image.jpg" \
    -F "boxDetections=[{\"topLeftX\":225,\"topLeftY\":469,
\"bottomRightX\":1454,\"bottomRightY\":1042}]" \
    http://localhost:8080/RESTServer/boxRecognition
```

### **Notes:**

Content type of the request is **multipart/form-data**, where the inputs are stored in the form data fields.

Input image is referenced with filepath (starting with @) in the form field **file**.

Optional parameters **roi** and **boxDetections** can be referenced with filepath (starting with @, referencing a text file containing JSON string) or can contain the whole JSON as a string (special characters must be escaped).

### **Response Example:**

### Automatic vehicle detection and recognition:

```
[
    "boxDetection":{
     "topLeftX": 207.98,
```

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```
"topLeftY": 254.33,
  "bottomRightX": 1550.75,
  "bottomRightY": 1209.36,
  "score": 0.9650459,
  "occlusion": 0.0010549
"mmrResult":{
  "view": "frontal",
  "viewID": 1,
  "viewScore": 0.9999329,
  "category": "CAR",
  "categoryID": 2,
  "categoryScore": 0.9997303,
 "make": "VW",
  "makeID": 43,
  "makeScore": 0.9999216,
  "model": "Passat",
  "modelID": 3569,
  "modelScore": 0.9990373,
  "generation": "Mk VI (2005)",
  "generationID": 3691,
  "generationScore": 0.9979515,
  "color": "WHITE",
  "colorID": 13,
  "colorScore": 0.94161636,
  "tags": [
      "name": "ambulance",
"value": "no",
      "id": 14,
      "score": 0.99998176
    },
      "name": "caravan",
"value": "no",
      "id": 10,
      "score": 0.99946773
    },
      "name": "fire_brigade",
      "value": "no",
      "id": 16,
      "score": 0.9999783
    },
      "name": "law enforcement",
      "value": "yes",
      "id": 11,
      "score": 1.0
      "name": "pickup",
      "value": "no",
      "id": 38,
      "score": 0.670191
      "name": "push_bumper",
      "value": "no",
      "id": 30,
      "score": 0.9948259
    },
      "name": "towed",
      "value": "no",
      "id": 51,
      "score": 0.99552554
```



### **Notes:**

When the **boxDetections** form field is provided in the request, the response elements **boxDetection** contain only the fields from the request: **topLeftX**, **topLeftY**, **bottomRightX** and **bottomRightY**.

If the **LPM Box Detector** engine is not running and the **boxDetections** form field is not provided in the request, an empty array is returned in the response.

Running the MMR Box based engine is required to obtain the mmrResult element in the response.

### **Response Definitions:**

The following table describes each item in the response.

Response item	Description	Data type
boxDetection	Information about the detected vehicle location in the input image.	Object
boxDetection/topLeftX	The horizontal coordinate of the top-left bounding box corner within the image.	Decimal number
boxDetection/topLeftY	The vertical coordinate of the top-left bounding box corner within the image.	Decimal number
boxDetection/bottomRightX	The horizontal coordinate of the bottom-right bounding box corner within the image.	Decimal number
boxDetection/bottomRightY	The vertical coordinate of the bottom-right bounding box corner within the image.	Decimal number
boxDetection/score	The vehicle detection confidence factor. Range $0-1$ .	Decimal number
boxDetection/occlusion	Specifies how much the detection is occluded. Range 0 (not occluded) – 1 (fully occluded).	Decimal number
boxDetection/truncated	Specifies whether the detection is truncated (the bounding box does not cover the whole object).	Boolean
boxDetection/clusterID	ID of a cluster, to which this detection belongs. Not yet implemented in the current LPM modules.	Integer
boxDetection/clusterScore	Confidence factor for clusterID prediction. Range 0 – 1.	Decimal number



mmrResult	Information about the recognized vehicle attributes.	Object
mmrResult/view	The recognized vehicle view, either "FRONTAL", or "REAR".	String
mmrResult/viewID	ID of the recognized vehicle view.	Integer
mmrResult/viewScore	The confidence factor for the view result. Range $0-1$ .	Decimal number
mmrResult/category	The recognized vehicle category, e.g., "BUS", "CAR", "HVT", For the full list of possible categories and their definition, check the Eyedea MMR SDK documentation.	String
mmrResult/categoryID	ID of the recognized vehicle category.	Integer
mmrResult/categoryScore	The confidence factor for the category result. Range $0-1$ .	Decimal number
mmrResult/ <b>make</b>	The recognized vehicle manufacturer, e.g., "VW", "Ford", "Fiat", For the full list of possible categories, check the Eyedea MMR SDK documentation.	String
mmrResult/makeID	ID of the recognized vehicle manufacturer.	Integer
mmrResult/makeScore	The confidence factor for the make result. Range $0-1$ .	Decimal number
mmrResult/model	The recognized vehicle model (vehicle instance defined by a bodywork), e.g., "Golf", "Mondeo", "500",	String
mmrResult/modelID	ID of the recognized vehicle model.	Integer
mmrResult/modelScore	The confidence factor for the model result. Range $0-1$ .	Decimal number
mmrResult/generation	The recognized vehicle generation (vehicle mark and first model year), e.g., "Mk VI (2019)", "Mk I (2020)",	String
mmrResult/generationID	ID of the recognized vehicle generation.	Integer
mmrResult/generationScore	The confidence factor for the generation result. Range $0-1$ .	Decimal number
mmrResult/variation	The recognized vehicle variation (vehicle trim level and/or body type), e.g., "AMG", "AMG-Line SUV", "Coupe",	String
mmrResult/variationID	ID of the recognized vehicle variation.	Integer
mmrResult/variationScore	The confidence factor for the variation result. Range $0-1$ .	Decimal number
mmrResult/ <b>colo</b> r	The recognized vehicle color, e.g., "BLUE", "GRAY", "RED",	String
mmrResult/colorID	ID of the recognized vehicle color.	Integer
	ı	



mmrResult/colorScore	The confidence factor for the color result. Range $0-1$ .	Decimal number
mmrResult/tags	An array of recognized vehicle traits.	Array of objects
mmrResult/tags/ <b>name</b>	The name of the trait, e.g., "caravan", "ambulance", For the full list of possible tags and their definition, check the Eyedea MMR SDK documentation.	String
mmrResult/tags/value	The value of the trait. Either "yes", or "no".	String
mmrResult/tags/id	ID of the trait value.	Integer
mmrResult/tags/score	The confidence factor for the tag value. Range $0-1$ .	Decimal number

